



# Robot Dress Kit Questionnaire

## Robot Make and Model

(example: Fanuc R2000iC-165F, Kuka KR210 R3100-2, ABB IRB 6700-2.6)

---

## Application

(example: welding, material handling, sealant, palletizing)

---

## Will Syndevco be required to provide utilities?

Yes

No

## Please specify all cables/ hoses and their OD sizes that need to be routed

(example: 1/4" air hose, 10 AWG cable, 8mm aux power cable)

---

---

---

---

---

## List any special robot considerations

(example: any equipment mounted on the robot)

---

---

---

---

---

## List any special cell considerations

(example: any space limitations, any equipment near the robot, anything the robot will interact with)

---

---

---

---

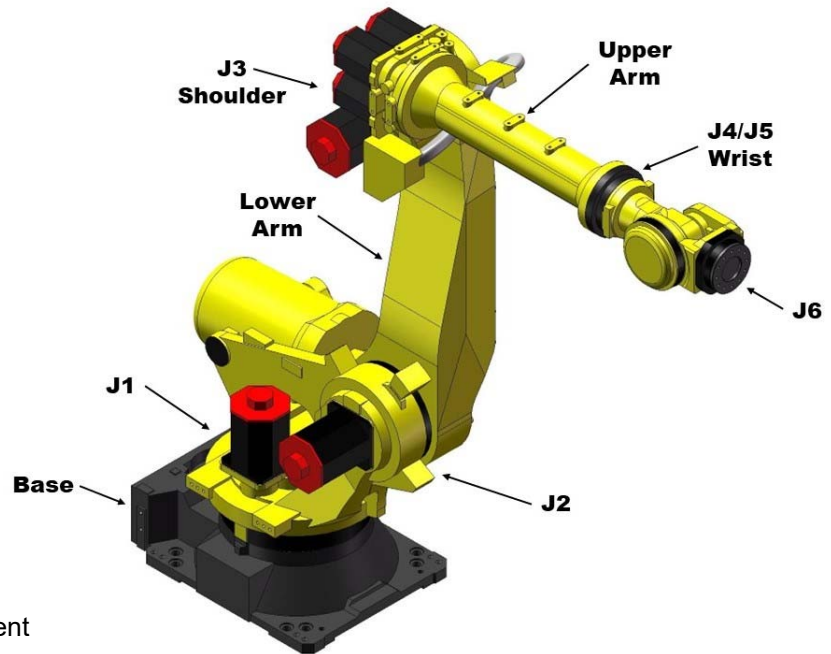
---

(continued on next page)

**What portions of the robot need to be dressed?**

(check all that apply, write any additional comments below)

- Base
- J1
- J2
- Lower Arm
- J3 Shoulder
- Upper Arm
- J4/ J5 Wrist
- J6
- Total Robot
- Include Off Robot Equipment



**Specify joint articulation**

(select all that apply, write any additional comments below)

- J1 rotation below 90 degrees (max +/- 45 degrees)
- J1 rotation below 180 degrees (max +/- 90 degrees)
- J1 rotation above 180 degrees (min +/- 90 degrees, maximum rotation may vary)
- J3 rotation above 180 degrees (+/- 90 degrees)
- J4/J5 rotation above 180 degrees (+/- 90 degrees)
- J6 rotation above 180 degrees (+/- 90 degrees)