



Robot Dress Kit Questionnaire

Robot Make and Model

(example: Fanuc R2000iC-165F, Kuka KR210 R3100-2, ABB IRB 6700-2.6)

_____ **Quantity:** _____

Application

(example: welding, material handling, sealant, palletizing)

Will Syndevco be required to provide utilities (cables/hoses)?

Yes

No

Please specify all cables/ hoses and their OD sizes that need to be routed

(example: 1/4" air hose, 10 AWG cable, 8mm aux power cable)

List any special robot considerations

(example: any equipment mounted on the robot)

List any special cell considerations

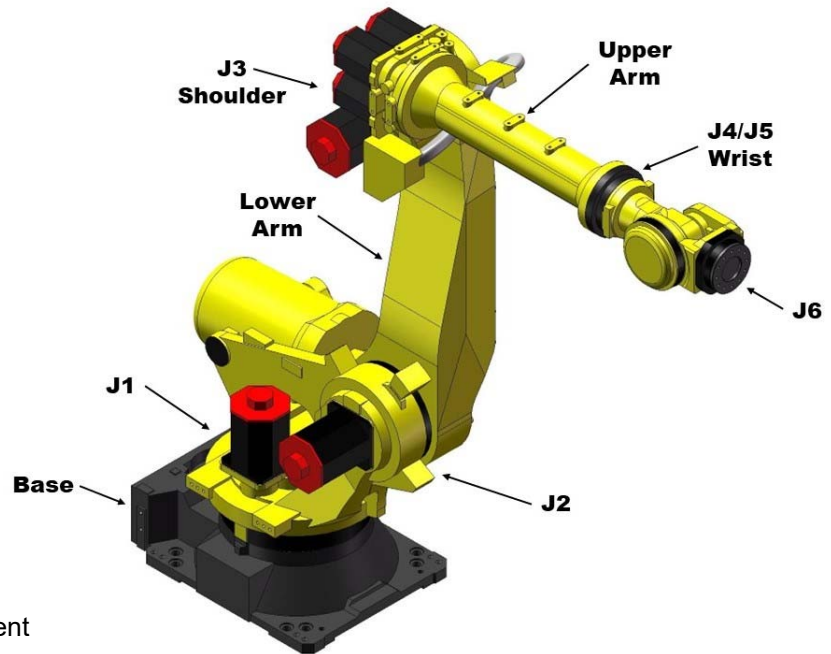
(example: any space limitations, any equipment near the robot, anything the robot will interact with)

(continued on next page)

What portions of the robot need to be dressed?

(check all that apply, write any additional comments below)

- Base
- J1
- J2
- Lower Arm
- J3 Shoulder
- Upper Arm
- J4/ J5 Wrist
- J6
- Total Robot
- Include Off Robot Equipment



Specify joint articulation

(select all that apply, write any additional comments below)

- J1 rotation below 90 degrees (max +/- 45 degrees)
- J1 rotation below 180 degrees (max +/- 90 degrees)
- J1 rotation above 180 degrees (min +/- 90 degrees, maximum rotation may vary)
- J3 rotation above 180 degrees (+/- 90 degrees)
- J4/J5 rotation above 180 degrees (+/- 90 degrees)
- J6 rotation above 180 degrees (+/- 90 degrees)

Is this an existing application looking for a retrofit?

(select all that apply, write any additional comments below)

- Yes
- No

Please provide any pictures/ videos/ drawings pertinent to this application